

In the Claims:

Claims 1 to 44 (Canceled).

1 45. (New) A method for controlling, in closed loop fashion, the
2 operation of an internal combustion engine including engine
3 cylinders, said method comprising the following steps:

- 4 a) sampling an engine speed signal,
5 b) applying a Hartley-transformation to said engine speed
6 signal for transforming said engine speed signal into
7 an angular frequency range,
8 c) analyzing said angular frequency range for producing
9 individual angular frequency orders representing phase
10 information and amplitude information,
11 d) performing a cylinder classification based on said
12 phase information and said amplitude information by
13 first comparing said phase information with a given
14 reference phase value and by second comparing said
15 amplitude information with a given first amplitude
16 threshold value, said first comparing and said second
17 comparing yielding individual cylinder informations
18 for each cylinder of said engine cylinders,
19 e) processing said individual cylinder informations for
20 identifying, based on said first phase comparing, any
21 cylinder which is causing an uneven running of said
22 internal combustion engine for further identifying,
23 also based on said first phase comparing, a fuel
24 adjustment direction for each individual cylinder

25 including said cylinder causing said uneven running,
26 and for determining, based on said second amplitude
27 comparing, an injection fuel quantity required for
28 correcting said uneven running of said internal
29 combustion engine,

30 f) generating in response to said processing a closed
31 loop control signal and applying said closed loop
32 control signal to an engine controller for correcting
33 said uneven running of said internal combustion
34 engine,

35 g) detecting a misfiring of any one of said engine
36 cylinders by further comparing said amplitude
37 information with a respective second given amplitude
38 threshold value to provide information for concluding
39 whether said uneven running is caused by said
40 misfiring when said amplitude information exceeds said
41 respective second given amplitude threshold value,

42 h) detecting an actual power output of said internal
43 combustion engine,

44 i) comparing said actual power output with a rated power
45 output of said internal combustion engine to provide
46 a reduced power output information,

47 j) modifying said closed loop control signal in response
48 to said reduced power output information, and

49 k) applying said modified closed loop control signal to
50 said engine controller for controlling a fuel
51 injection to all said engine cylinders for correcting

52 said actual power output with reference to said rated
53 power output.

1 46. (New) The method of claim 45, further comprising assuring
2 that operating parameters of said internal combustion
3 engine differ insignificantly from each other at a
4 beginning and at an end of said sampling of said engine
5 speed signal, performing said sampling so that at least two
6 sequential speed signal segments are sampled, and forming
7 a mean value of said at least two sequential speed signal
8 segments.

1 47. (New) The method of claim 46, wherein said forming of a
2 mean value is performed to obtain an arithmetic mean value.

1 48. (New) The method of claim 45, further comprising correcting
2 any one of said individual angular frequency orders and
3 said given reference phase value by performing the
4 following substeps: temporarily stopping any fuel injection
5 to said internal combustion engine to cause a towed
6 operation, and performing said correcting as a towed
7 correction for eliminating any parasitic effects from any
8 one of said individual angular frequency orders and said
9 given reference phase value.

1 49. (New) The method of claim 45, further comprising performing
2 said step (g) of detecting said misfiring by selecting out
3 of said individual angular frequency orders low frequency

individual angular frequency orders and deriving said amplitude information from said low frequency individual angular orders for said comparing to determine a misfiring cylinder.

50. (New) The method of claim 45, further comprising performing the following substeps for said detecting of said misfiring of any one of said engine cylinders, providing speed and load dependent reference phases, combining said speed and load dependent reference phases to form a calibration factor, correlating said speed and load dependent reference phases to respective measured phases of said individual angular frequency orders for designating one of said engine cylinders as a first cylinder, and identifying said misfiring cylinder by taking into account said speed and load dependent reference phases, said calibration factor, knowledge of which cylinder is said first cylinder and that said amplitude information has exceeded said respective second given amplitude threshold value of step (g).

51. (New) The method of claim 50, wherein said individual angular frequency orders representing phase and amplitude information include at least an 0.5th order and a 1.0st order, and further comprising correlating said speed and load dependent reference phases to measured phases of said 0.5th order and said 1.0st order, so that a speed and load dependent reference phase of the 0.5th order that is

8 closest to the measured phase of the 0.5th order designates
9 said first cylinder.

1 52. (New) The method of claim 45, further comprising
2 establishing said rated power output by taking respective
3 amplitude measurements from a reference engine, storing
4 said amplitude measurements as a function of speed in a
5 memory to provide said rated power output for use in said
6 comparing in said step (i).

1 53. (New) An apparatus for controlling, in a closed loop
2 control, the operation of an internal combustion engine, by
3 performing the method of claim 45 said apparatus
4 comprising: a speed signal sampling sensor (3) for
5 generating an engine speed signal, a frequency analyzer (5)
6 having an input for receiving said engine speed signal for
7 performing a Hartley-transformation on said engine speed
8 signal thereby converting said engine speed signal into an
9 angular frequency range, said frequency analyzer (5)
10 producing from said angular frequency range individual
11 angular frequency orders, a cylinder classifier (7) having
12 an input connected to an output of said frequency analyzer
13 (5), and a controller (8) having an input connected to an
14 output of said cylinder classifier for receiving an input
15 signal from said cylinder classifier for generating a
16 closed loop control signal, said controller (8) having an
17 output connected to said internal combustion engine for
18 said closed loop control, wherein said signal sampler

19 sensor (3), said frequency analyzer (5) and said cylinder
20 classifier (7) are adapted for detecting a misfiring
21 cylinder of said internal combustion engine, and wherein
22 said signal sampler sensor (3), said frequency analyzer
23 (5), said cylinder classifier (7) and said controller (8)
24 are further adapted for generating closed loop control
25 signals for said internal combustion engine for tracking
26 any one of an engine torque and an engine power output.

1 54. (New) The apparatus of claim 53, further comprising a
2 computer (4) operatively interposed between said signal
3 sampler sensor (3) and said frequency analyzer (5) for
4 calculating an arithmetic mean value of a plurality of said
5 individual angular frequency orders.

1 55. (New) The apparatus of claim 53, further comprising a
2 frequency corrector (6) operatively interposed between said
3 frequency analyzer (5) and said cylinder classifier (7) for
4 correcting said individual angular frequency orders.

1 56. (New) The apparatus of claim 53, wherein said cylinder
2 classifier (7) comprises a generator (71) for generating
3 reference phases, a calibrator (72) for calibrating said
4 reference phases, and a selector (73) for selecting a
5 reference phase, said cylinder classifier (7) further
6 comprising means (74) for determining weighting factors,
7 means (75) for determining any one of primary and secondary
8 causers of any one of a disturbance and a deviation, and

9 means (76) for generating qualitative fuel injection
10 adjustment control signals for adjusting a fuel supply for
11 said internal combustion engine, said generating of said
12 fuel injection adjustment control signals taking into
13 account any one of qualitative and quantitative parameters.

1 57. (New) The apparatus of claim 53, wherein said controller
2 (8) comprises any one of an I-control circuit and a
3 PI-control circuit.

[RESPONSE CONTINUES ON NEXT PAGE]